

A generic approach to topic models

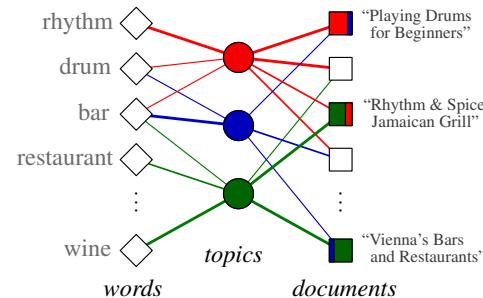
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Vienna, 1 June 2012

- Topic models – motivation and review
- Networks of mixed membership (NoMMs)
- Inference – a Gibbs “meta-sampler”
- NoMM typology and design
- Application to tag-enhanced expertise finding
- Conclusions and outlook

Topic models

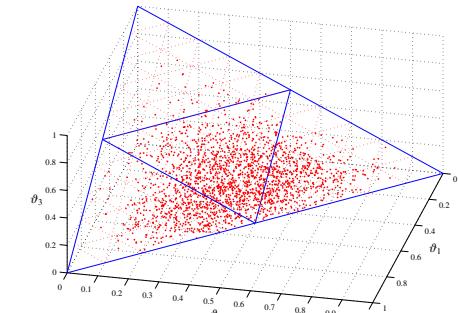


- Probabilistic representations of grouped discrete data
- Illustrative for text: words grouped in documents
 - Latent topics (a.k.a. concepts, components) = cluster semantically related words (Landauer and Dumais 1997; Griffiths et al. 2007)
 - Language = semantic meaning (topics) + noise
- Reduce **vocabulary problem** by discovery of semantic relations
- Reduce **sparsity problem** by dimensionality reduction ↔ discrete principal components analysis (Buntine and Jakulin 2005)

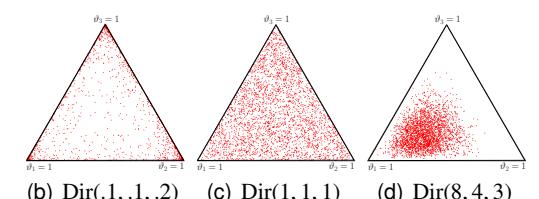
Towards Bayesian topic models: the Dirichlet distribution

Bayesian methodology:

- Parameters generated from *prior* distributions
- Language data: popular prior for the multinomial / discrete distribution: Dirichlet distribution
 - Conjugacy: straight-forward mathematical form
- Bayesian topic model: Latent Dirichlet allocation (Blei et al. 2003)

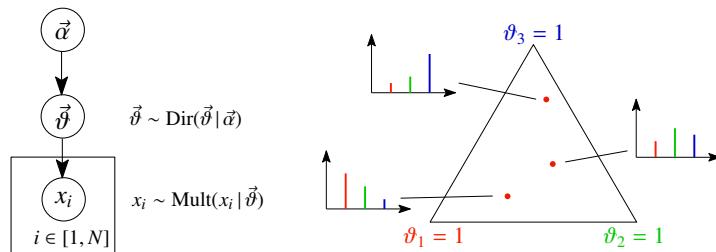


(a) $\text{Dir}(4, 4, 2)$



(b) $\text{Dir}(.1, .1, .2)$ (c) $\text{Dir}(1, 1, 1)$ (d) $\text{Dir}(8, 4, 3)$

Bayesian networks: Dirichlet-generated multinomials



Bayesian networks:

- Graphical modelling of joint probability distributions
- Node: random variable
- Edge: conditional probability distribution
- Plate: repeated i.i.d. samples

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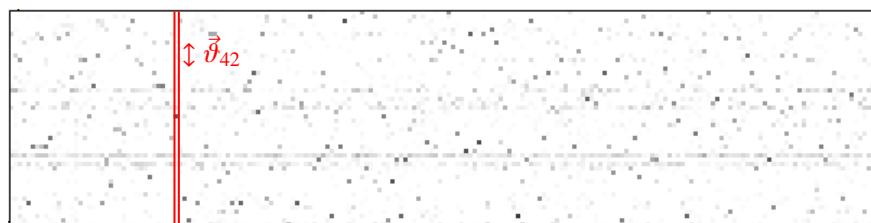
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Example document–topic distributions

Document $m = 42$ (column): Traditional machine learning relies on the availability of a large amount of data to train a model, which is then applied to test data in the same feature space. However, labeled data are often scarce and expensive to obtain...

Strongest topics: $k = \{25, 21, 48, \dots\}$



transposed view: rows = topics, columns = documents

Figure: Excerpt from document–topic matrix ϑ ($M = 200, K = 50$).

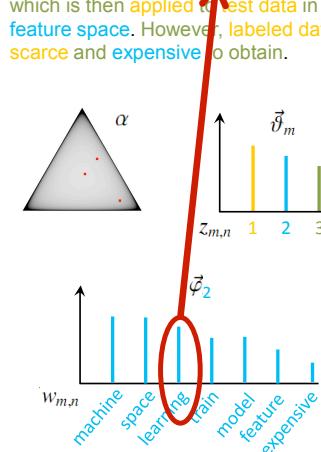
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Latent Dirichlet Allocation

Traditional **machine learning** relies on the availability of a large amount of data to **train** a model, which is then **applied** to **test** data in the same **feature space**. However, **labeled data** are often **scarce** and **expensive** to obtain.



Draw word from term distribution of topic 2, "learning"

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Example topic–term distributions

Topic $k = 21$ (row): data word feature label data scarce obtain...

Topic $k = 25$ (row): machine learning train model test feature space...

Topic $k = 48$ (row): computing support grant project system method...

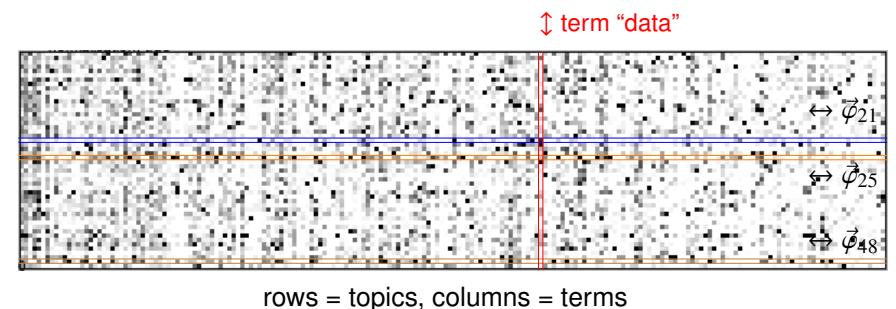


Figure: Excerpt from topic–term matrix φ ($V = 200, K = 50$).

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Example: Text mining for semantic clusters

Topic label	Most likely terms according to $\varphi_{k,t} = p(\text{word} \text{topic})$
Politische Parteien	CDU Partei Kohl Aufklärung Schäuble Zeitung Union Krise Wahrheit Affäre Christdemokraten Glaubwürdigkeit Konsequenzen
Bundesliga	FC SC München Borussia SV VfL Kickers SpVgg Uhr Köln Bochum Freiburg VfB Eintracht Bayern Hamburger Bayern+München
Polizei / Unfall	Polizei verletzt schwer Auto Unfall Fahrer Angaben schwer+verletzt Menschen Wagen Verletzungen Lawine Mann vier Meter Straße
Tschetschenien	Rebellen russischen Grosny russische Tschetschenien Truppen Kaukasus Moskau Angaben Interfax Tschetschenischen Agentur
Politik / Hessen	FDP Koch Hessen CDU Koalition Gerhardt Wagner Liberalen hessischen Westerwelle Wolfgang Roland+Koch Wolfgang+Gerhardt
Wetter	Grad Temperaturen Regen Schnee Süden Norden Sonne Wetter Wolken Deutschland zwischen Nacht Wetterdienst Wind
Politik / Kroatien	Parlament Partei Stimmen Mehrheit Wahlen Wahl Opposition Kroatien Präsident Parlamentswahl Mesic Abstimmung HDZ
Die Grünen	Grünen Parteitag Atomaustritt Tritin Grüne Partei Trennung Mandat Ausstieg Amt Roestel Jahren Müller Radcke Koalition
Russische Politik	Russland Putin Moskau russischen russische Jelzin Wladimir Tschetschenien Russlands Wladimir+Putin Kreml Boris Präsidenten
Polizei / Schulen	Polizei Schulen Schüler Täter Polizisten Schule Tat Lehrer erschossen Beamten Mann Polizist Beamte verletzt Waffe

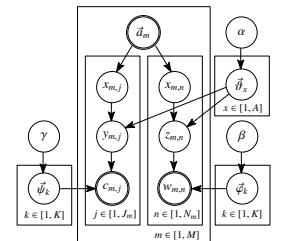
Bigram LDA topics, 18400 German news messages, Jan. 2000 (Heinrich et al. 2005)

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Typical derivation method (Is it really that complex?)



(e) Expert–tag–topic model (ETT)

(Heinrich 2011)

$$p(\vec{w}, \vec{c}, \vec{d}, \vec{x}, \vec{\theta}, \vec{\phi}, \vec{\psi} | \alpha, \beta, \gamma) = \int \int \int \prod_{m=1}^M \prod_{n=1}^{N_m} \prod_{j=1}^{J_m} p(w_{m,n} | \vec{\varphi}_{y_{m,n}}) p(z_{m,n} | \vec{\theta}_{x_{m,n}}) a_{m,x_{m,n}}$$

$$\cdot \prod_{j=1}^{J_m} p(c_{m,j} | \vec{\varphi}_{y_{m,n}}) p(y_{m,j} | \vec{\theta}_{x_{m,n}}) a_{m,x_{m,n}} \quad (\text{E.4})$$

$$= \int \prod_{m=1}^M \prod_{n=1}^{N_m} p(w_{m,n} | \vec{\varphi}_{y_{m,n}}) \prod_{k=1}^K p(\vec{\varphi}_k | \theta) d\vec{\varphi}_k$$

$$\cdot \prod_{m=1}^M \prod_{n=1}^{N_m} \prod_{j=1}^{J_m} p(c_{m,j} | \vec{\varphi}_{y_{m,n}}) \prod_{k=1}^K p(\vec{\varphi}_k | \theta) d\vec{\varphi}_k$$

$$\cdot \int \prod_{m=1}^M p(\vec{\theta} | \alpha) \prod_{n=1}^{N_m} p(z_{m,n} | \vec{\theta}_{x_{m,n}}) a_{m,x_{m,n}} \prod_{j=1}^{J_m} p(y_{m,j} | \vec{\theta}_{x_{m,n}}) a_{m,x_{m,n}} d\vec{\theta} \quad (\text{E.5})$$

$$= \int \prod_{k=1}^K \frac{1}{\Delta_K(\beta)} \prod_{j=1}^{J_m} \frac{1}{\Delta_{x_{m,n}}(\beta)} \prod_{n=1}^{N_m} \frac{1}{\Delta_{y_{m,n}}(\beta)} d\vec{\theta}_k \int \prod_{k=1}^K \frac{1}{\Delta_K(\alpha)} \prod_{n=1}^{N_m} \frac{1}{\Delta_{x_{m,n}}(\alpha)} d\vec{\theta}_k$$

$$\cdot \int \prod_{n=1}^A \frac{1}{\Delta_K(\alpha)} \prod_{k=1}^K \frac{\theta_{x_{m,n}}^{(1)} + \theta_{x_{m,n}}^{(2)} + \dots + \theta_{x_{m,n}}^{(A)}}{\theta_{x_{m,n}}^{(1)} + \theta_{x_{m,n}}^{(2)} + \dots + \theta_{x_{m,n}}^{(A)}} d\vec{\theta}_k \cdot \prod_{m=1}^M \prod_{n=1}^{N_m} \frac{\theta_{y_{m,n}}^{(1)} + \theta_{y_{m,n}}^{(2)} + \dots + \theta_{y_{m,n}}^{(J_m)}}{\theta_{y_{m,n}}^{(1)} + \theta_{y_{m,n}}^{(2)} + \dots + \theta_{y_{m,n}}^{(J_m)}} d\vec{\theta}_k \quad (\text{E.6})$$

$$= \prod_{k=1}^K \frac{\Delta(\theta_k^{(1)} + \beta)}{\Delta(\theta_k^{(1)} + \alpha)} \cdot \frac{\Delta(\theta_k^{(2)} + \beta)}{\Delta(\theta_k^{(2)} + \alpha)} \cdots \prod_{n=1}^{N_m} \frac{\Delta(\theta_{y_{m,n}}^{(1)} + \theta_{y_{m,n}}^{(2)} + \dots + \theta_{y_{m,n}}^{(J_m)} + \alpha)}{\Delta(\theta_{y_{m,n}}^{(1)} + \theta_{y_{m,n}}^{(2)} + \dots + \theta_{y_{m,n}}^{(J_m)} + \beta)} \prod_{m=1}^M \prod_{n=1}^{N_m} a_{m,x_{m,n}} \quad (\text{E.6})$$

$$p(z_i=k, x_j=x | w_i, t, z_{-i}, \vec{x}_{-i}, \vec{w}_{-i}, \vec{d}, \vec{\theta}, \vec{\phi}) = \frac{p(w_i | \vec{\varphi}_{y_{i,j}}) p(z_i=k | \vec{\theta}_{x_{i,j}}) a_{m,x_{i,j}}}{p(w_i | \vec{\varphi}_{y_{i,j}}) p(z_i=k | \vec{\theta}_{x_{i,j}}) a_{m,x_{i,j}}} \cdot \frac{p(\vec{\varphi}_{y_{i,j}})}{p(\vec{\varphi}_{y_{i,j}})} \cdot \frac{p(\vec{\theta}_{x_{i,j}})}{p(\vec{\theta}_{x_{i,j}})} \quad (\text{E.7})$$

$$\propto \frac{\Delta(\theta_k^{(i,j)} + \beta)}{\Delta(\theta_k^{(i,j)} + \alpha)} \cdot \frac{\Delta(\theta_{x_{i,j}}^{(i,j)} + \alpha)}{\Delta(\theta_{x_{i,j}}^{(i,j)} + \beta)} \cdot a_{m,x_{i,j}} \quad (\text{E.8})$$

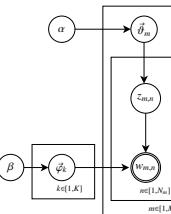
$$= \frac{\Gamma(n_{k,i,j} + \beta) \Gamma(n_{k,i,j} + V\beta)}{\Gamma(n_{k,i,j} + \beta) \Gamma(n_{k,i,j} + V\beta)} \cdot \frac{\Gamma(\theta_{x_{i,j}}^{(i,j)} + \alpha) \Gamma(\theta_{x_{i,j}}^{(i,j)} + K\alpha)}{\Gamma(\theta_{x_{i,j}}^{(i,j)} + \alpha) \Gamma(\theta_{x_{i,j}}^{(i,j)} + K\alpha)} \cdot a_{m,x_{i,j}} \quad (\text{E.9})$$

$$= \frac{n_{k,i,j} + \beta}{n_{k,i,j} + V\beta} \cdot \frac{n_{x_{i,j}}^{(i,j)} + \alpha}{n_{x_{i,j}}^{(i,j)} + K\alpha} \cdot a_{m,x_{i,j}} \quad (\text{E.10})$$

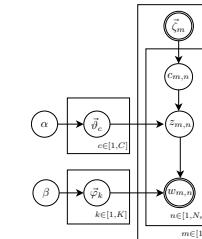
$$\cdot p(\vec{\theta} | \alpha) \cdot p(\vec{\phi} | \beta) \cdot p(\vec{\psi} | \gamma) \quad (\text{E.11})$$

$$p(y_j=k, x_j=x | c_i=c, \vec{z}_{-i}, \vec{x}_{-i}, \vec{w}, \vec{d}, \vec{\theta}, \vec{\phi}) = \frac{n_{k,c,j} + \gamma}{n_{k,c,j} + V\gamma} \cdot \frac{n_{x_{i,j}}^{(i,j)} + \alpha}{n_{x_{i,j}}^{(i,j)} + K\alpha} \cdot a_{m,x_{i,j}} \quad (\text{E.12})$$

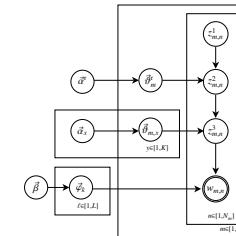
Topic models: Example structures



(a) Latent Dirichlet allocation (LDA)

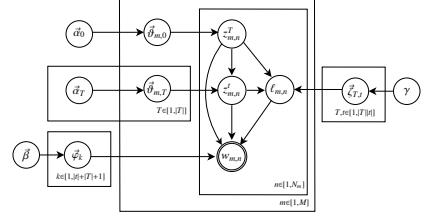


(b) Author–topic model (ATM)



(c) Pachinko allocation model (PAM4)

(Blei et al. 2003; Rosen-Zvi et al. 2004; Li and McCallum 2006; Li et al. 2007)



(d) Hierarchical PAM (hPAM)

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Topic models – bottom line

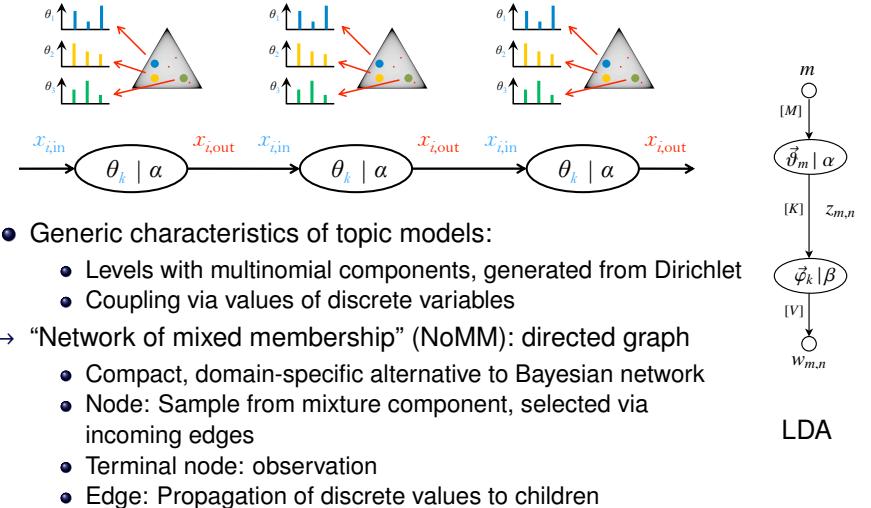
- Expanding research field with practical relevance
- No existing analysis as generic model class

→ Conjecture:

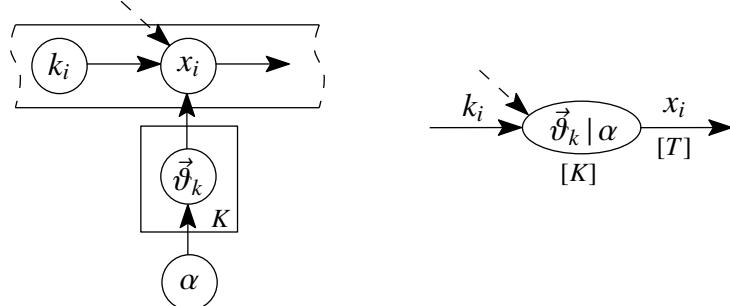
- Important properties generic across models
- Simplifications in the derivation of model properties, inference algorithms and design methods

- Topic models – motivation and review
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Generic topic models – “NoMMs”

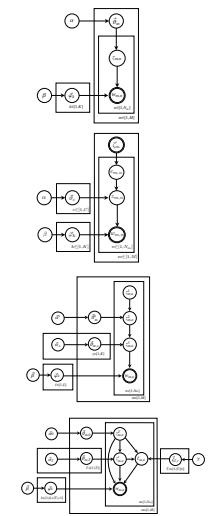
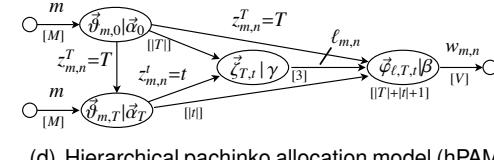
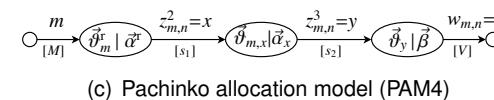
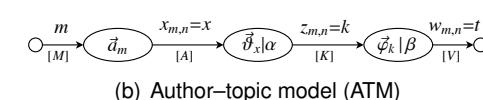
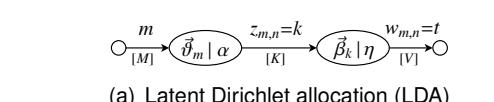


NoMM level notation



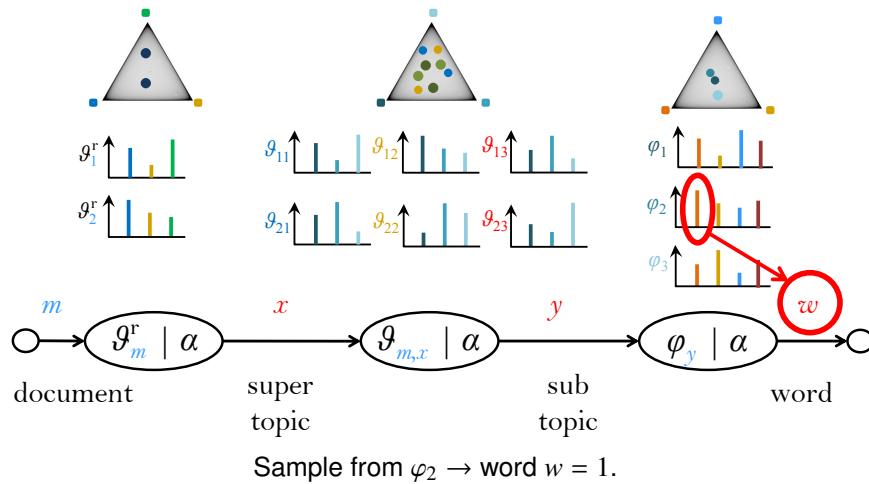
parameters + hyperparameters \Leftrightarrow nodes
variables \Leftrightarrow edges
plates \Leftrightarrow indices + dimensions

Topic models in NoMM representation



(Blei et al. 2003; Rosen-Zvi et al. 2004; Li and McCallum 2006; Li et al. 2007)

Example NoMM generative process: PAM4

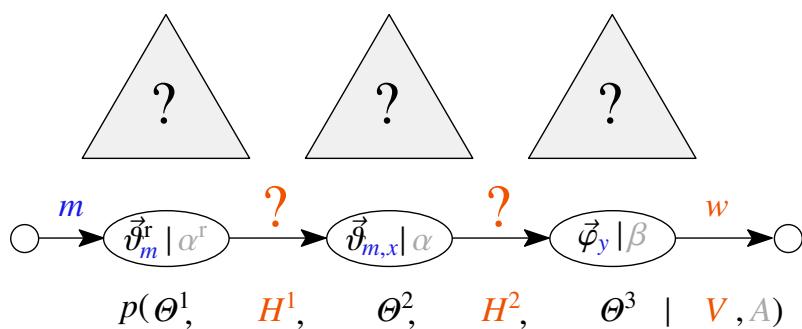


Overview

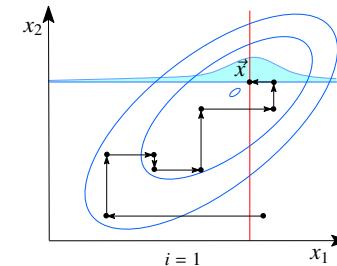
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Bayesian inference problem

- Bayesian inference: “Reverse generative process”
- Estimate (distributions over) parameters Θ and latent variables (“topics”) H given observations V and hyperparameters A .
- Find posterior distribution $p(H, \Theta | V, A) \rightarrow$ exponential complexity!

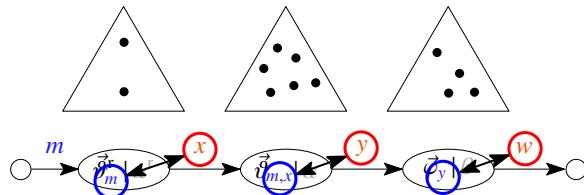


Collapsed Gibbs sampling



- Collapsed Gibbs sampling: stochastic EM / MCMC:
 - NoMMs: parameters Θ correlated with $H \rightarrow$ integrated out
 - For each data token i : Sample latent variables $H_i = (y_i, z_i, \dots)$, given all other data, latent H_{-i} and visible V :
- $$H_i \sim p(H_i | H_{-i}, V, A). \quad (1)$$
- Stationary state: full conditional simulates posterior
 - Faster absolute convergence for NoMMs than, e.g., variational Bayes (Heinrich and Goesele 2009)

Collapsed Gibbs full conditionals



- NoMM full conditionals can be generically derived (Heinrich 2009)
- Typical case leads to weights with straight-forward factor structure:

$$p(H_i | H_{\neg i}, V, A) \propto \prod_{\ell} \left[\frac{n_{k,t}^{-i} + \alpha}{n_k^{-i} + T\alpha} \right]^{\ell}. \quad (2)$$

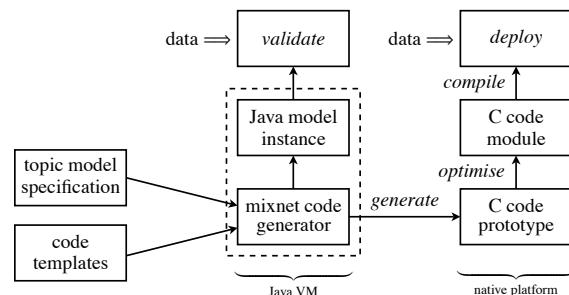
- $n_{k,t}$ = count of co-occurrences between **input** and **output** values of a NoMM level ℓ
- More generally: $p(H_i | \cdot) \propto \prod_{\ell} [q(k, t)]^{\ell}$ with t = set of values/edges

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Implementation: Gibbs “meta-sampler”



- Code generator for topic models in Java and C
- Separation of knowledge domains: topic model applications vs. machine learning vs. computing architecture

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q -functions and Pólya urn

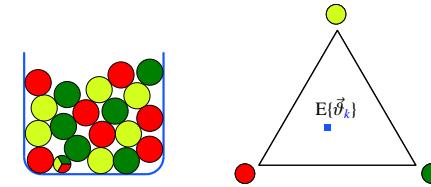


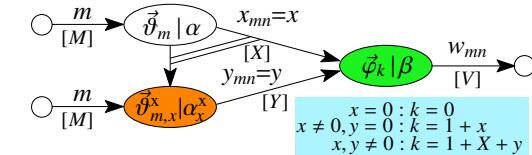
Figure: Pólya urn and multinomial parameters.

$$\begin{aligned} q(k, t) &\triangleq \frac{B(\vec{n}_k + \alpha)}{B(\vec{n}_k^{-i} + \alpha)} \stackrel{|t|=1}{=} \frac{n_{k,t}^{-i} + \alpha}{n_k^{-i} + T\alpha} = \text{smoothed ratio of co-occurrence counts} \\ &\stackrel{t=\{u,v\}}{=} \frac{n_{k,u}^{-i} + \alpha}{n_k^{-i} + T\alpha} \cdot \frac{n_{k,v}^{-i} + \alpha + \delta(u - v)}{n_k^{-i} + T\alpha + 1} \triangleq q(k, u \oplus v) \\ &\dots \end{aligned}$$

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Example NoMM script and generated kernel: hPAM2

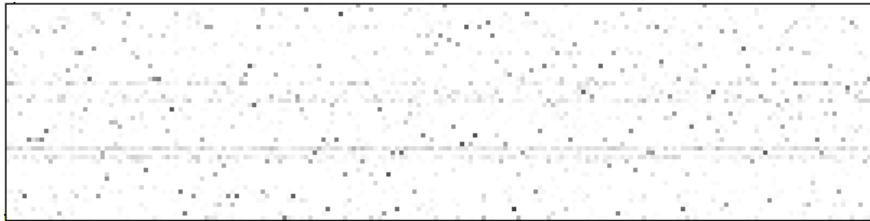


```

model = HPAM2
description:
  Hierarchical PAM model 2 (HPAM2)
sequences:
  # variables sampled for each (m,n)
  w, x, y : m, n
network:
  # each line one NoMM node
  m >> theta | alpha >> x
  m,x >> thetax | alphax[x] >> y
  x,y >> phi[k] >> w
  # java code to assign k
  k : {
    if (x==0) { k = 0; }
    else if (y==0) k = 1 + x;
    else k = 1 + X + y;
  }.
// hidden edge
for (hx = 0; hx < X; hx++) {
  // hidden edge
  for (hy = 0; hy < Y; hy++) {
    mxsel = X * m + hx;
    mxjsel = hx;
    if (hx == 0)
      ksel = 0;
    else if (hy == 0)
      ksel = 1 + hx;
    else
      ksel = 1 + X + hy;
    pp[hx][hy] = (nmx[m][hx] + alpha[hx])
    * (nmxy[mxsel][hy] + alphax[mxsel][hy])
    / (nmxysum[mxsel] + alphaxsum[mxsel])
    * (nkw[ksel][w[m][n]] + beta)
    / (nkw[ksel] + betasum);
    psum += pp[hx][hy];
  } // for h
} // for m
  
```

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Example document-topic distributions



$t = 500$, converged

Figure: Excerpt from document-topic matrix ϑ ($M = 200, K = 50$).

Overview

- Topic models – motivation and review
- Networks of mixed membership (NoMMs)
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Fast sampling: hybrid acceleration methods

Serial:

- Exploit saliency of few weights, e.g., generalising (Porteous et al. 2008): compute only few weights on average + estimate normalisation term
- Complex data structures, especially for larger models

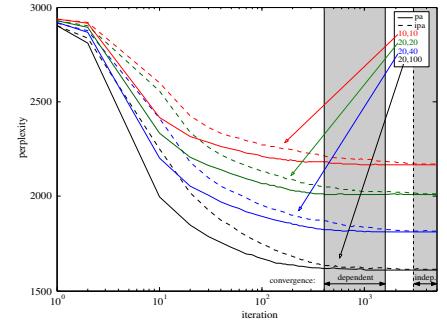
Parallel:

- Distribute local parameters (document-specific etc.)
- Need to sync global parameters: different methods, e.g., generalising (Newman et al. 2009)
- Occupancy: balance communication and computation (architecture-spec.)

Independence assumption:

- Reduce complexity: $\prod_\ell T^\ell \gg \sum_\ell T^\ell$

method	model	parameters	speedup (iter., converge)
S×P4	LDA	$K = 100$	6.3
S×P4	LDA	$K = 500$	30.2
I	PAM4	$K, L = 40, 40$	21.8
P4×I	PAM4	$K, L = 40, 40$	78.7
S×P4×I	PAM4	$K, L = 40, 40$	163.2
S×P4×I	PAM4	$K, L = 20, 100$	49.8
			43.5



→ Extend code generation to more complex implementations

q -functions and Pólya urn revisited

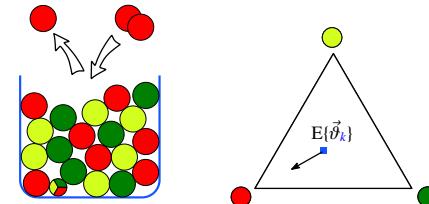


Figure: Pólya urn and multinomial parameters.

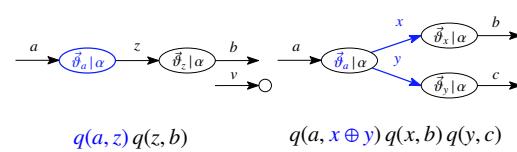
$$q(\mathbf{k}, \mathbf{t}) \triangleq \frac{B(\vec{n}_{\mathbf{k}} + \alpha)}{B(\vec{n}_{\mathbf{k}}^{-i} + \alpha)} \stackrel{|t|=1}{=} \frac{n_{\mathbf{k}, \mathbf{t}}^{-i} + \alpha}{n_{\mathbf{k}}^{-i} + T\alpha} = \text{smoothed ratio of co-occurrence counts}$$

$$\stackrel{t=\{u, v\}}{=} \frac{n_{\mathbf{k}, \mathbf{u}}^{-u_i} + \alpha}{n_{\mathbf{k}}^{-u_i} + T\alpha} \cdot \frac{n_{\mathbf{k}, \mathbf{v}}^{-v_i} + \alpha + \delta(\mathbf{u} - \mathbf{v})}{n_{\mathbf{k}}^{-v_i} + T\alpha + 1} \triangleq q(\mathbf{k}, \mathbf{u} \oplus \mathbf{v})$$

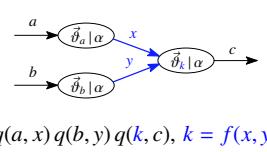
...

NoMM sub-structure typology

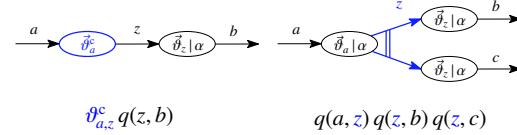
N1. Dirichlet–multinomial parameters E2. Autonomous edges



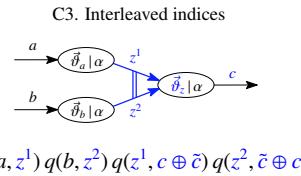
C2. Combined indices



N2. Observed parameters



E3. Coupled edges



Gibbs full conditional assembled via:

$$p(H_i | \cdot) \propto \prod_{\ell} \left[q(\textcolor{blue}{k}, \textcolor{red}{t}) \right]^{\ell} \quad (3)$$

Towards a design process

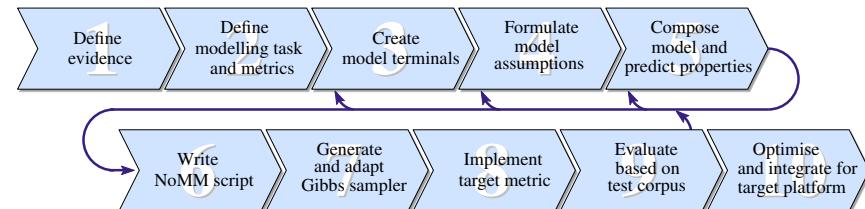
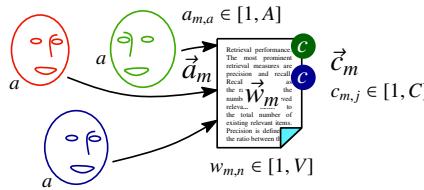


Figure: NoMM design process.

Name	Structure diagram	Gibbs sampler weight, w , Likelihood for single token i
N1, EI, CI.		$w(z) = q(a_i, \psi_i, b_i)$ $EI(z) = q(a_i, \theta_{1,1}, \theta_{1,2}, \dots, \theta_{1,n})$ $EI[\not]z = q(a_i, \theta_{2,1}, \theta_{2,2}, \dots, \theta_{2,n})$
Dir-Mult, unanchored		Mixture distribution: $D(\theta \text{Beta}(\alpha, \beta))$ [LDA (Blei et al. 2003b), PMI (Li & McCallum 2006); LDA (Blei et al. 2003b, 2006) (HLS)]
N2		Label distribution: ATM [Rosen-Zvi et al. 2004]
Observed parameters		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = p(a_i, \psi_i, b_i)$
N3, Non-Dirichlet prior		$w(z) = p(a_i, \psi_i, b_i)$ M-step estimate $\hat{\theta}_{bi} = \langle b_i \rangle$ [Blei & Lafferty 2007]
N4, Non-discrete output		$w(z) = p(a_i, \psi_i, b_i)$ Alternative distribution on the simplex: CTM [Blei & Lafferty 2007] - exp $\langle \theta_i \rangle / \sum_j \exp\langle \theta_j \rangle$ [LDA (Wallach 2008); hierarchy of Dirichlet priors]
N5+E4, Aggregation		$w(z) = p(a_i, \psi_i, b_i)$ M-step estimate $\hat{\theta}_{bi} = \langle b_i \rangle$ [Blei & Lafferty 2007]
E2, Autonomous edges		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ M-step estimate $\hat{\theta}_{bi} = \langle b_i \rangle$ [Zhang (2004); Poisson (2005); p(y b_i, LDA (Blei et al. 2003), GMM (McLachlan et al. 2000))]
E3, Coupled edges		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ M-step estimate $\hat{\theta}_{bi} = \langle b_i \rangle$ [Zhang (2004); Poisson (2005); p(y b_i, LDA (Blei et al. 2003), GMM (McLachlan et al. 2000))]
C2, Combined indices		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ Common cause for observations: Hidden relational model (HRM) [Xu et al. 2004; Link-LADA (Erosheva et al. 2004)]
C3, Interleaved indices		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ Common cause for observations: Hidden relational model (HRM) [Xu et al. 2004; Link-LADA (Erosheva et al. 2004)]
C4, Switch		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ Selbstreferentielle Multinomial LDA [Trovò & McDonald 2008], Entopic models [Newman et al. 2006]
C5, Node coupling		$w(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ CSA: $b_i(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ CSA: $b_i(z) = p(a_i, \psi_i, b_i)$ $b_i(z) = \sum_k \theta_{i,k} b_{i,k}$ p(c, d, b) = $\sum_k \theta_{i,k} \theta_{j,k} \theta_{c,k} \theta_{d,k}$ Correlation of submodels: relations: Simple relational component model [Stanfill et al. 2008]; Relational topic model [Chang & Blei 2009]

Define evidence

- Expertise finding in digital libraries
 - Find authors from document content
 - Semantic tags to disambiguate word meaning and provide additional retrieval method



- Example: scientific community of *Neural Information Processing Systems (NIPS)* conference

Propagation Algorithms for Variational Bayesian Learning

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Abstract

Variational approximations are becoming a widespread tool for Bayesian learning of graphical models. We provide some theoretical results for the variational updates in a very general class of complete Bayesian graphical models. We show how the belief propagation and the junction tree algorithms can be used in the inference process. We also show how the variational approximation results to the Bayesian analysis of linear-Gaussian state-space models we obtain a learning procedure that exploits the Kalman smoothing and filtering framework. In addition to these theoretical results, we demonstrate how this can be used to infer the hidden state dimensions and parameters for a variety of synthetic problems and one real high-dimensional data set.

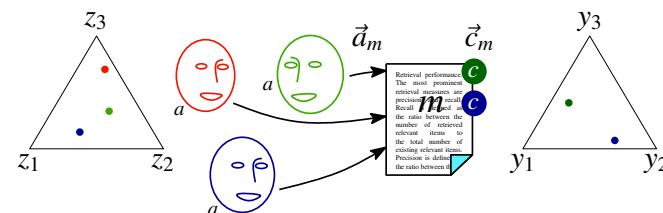
1 Introduction

Bayesian approaches to machine learning have several desirable properties. Bayesian integration does not suffer overfitting (since nothing is fit to the data). Prior knowledge can be incorporated naturally and all uncertainty is manipulated in a consistent manner. Moreover it is possible to obtain standard errors and readily compare different models. Unfortunately, for most models of interest Bayesian analysis is computationally intractable.

Until recently, approximate approaches to the intractable Bayesian learning problem had been based on Markov Chain Monte Carlo (MCMC) sampling, the Laplace approximation (Gaussian integration), or asymptotic penalties like BIC. The recent advent of variational methods has changed this situation. There is now a large body of papers showing that these methods can be used to rapidly learn the model structure and approximate the evidence in a wide variety of models. In this paper we will not motivate advantages of the variational Bayesian approach as this is done in

Tags: *probabilistic methods, variational inference, learning algorithms*

Modelling assumptions



- Expertise of authors weighted by the portion of authorship $a_{m,a}$.
- Expertise semantics expressed by topics z . Each author has a single field of expertise (topic distribution).
- Tag semantics expressed by topics y . Tag topics y could be $\equiv z$.

Define tasks + metrics; set up terminals

- Retrieval of experts a for term queries \vec{w} and tag queries \vec{c} : query likelihood model: $p(\vec{w}|a)$ and $p(\vec{c}|a) \rightarrow$ measure retrieval precision
- Topic quality \rightarrow measure coherence score
- Baseline: Author-topic model ATM (Rosen-Zvi et al. 2004), LDA (Blei et al. 2003)

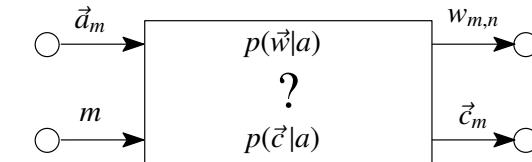
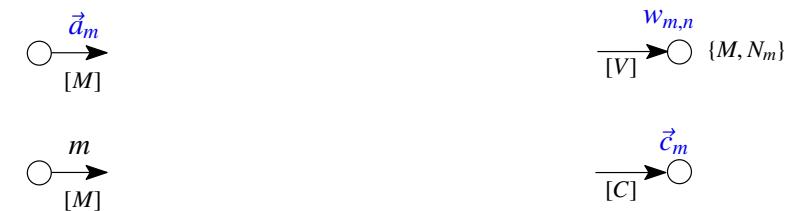


Figure: Model design: Terminals.

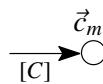
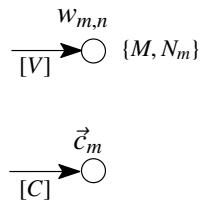
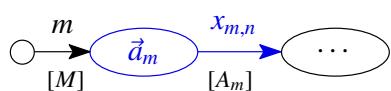
Compose model



$$p(\dots | \vec{a}, \vec{w}, \vec{c}) \propto \dots$$

Starting from terminals

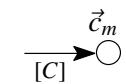
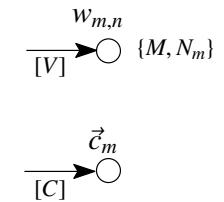
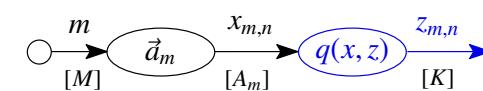
Compose model



$$p(\mathbf{x}, \dots | \cdot) \propto a_{m,x} q(\mathbf{x}, \dots) \dots$$

Up-stream evidence \vec{d}_m
 → observed parameter node samples word author x

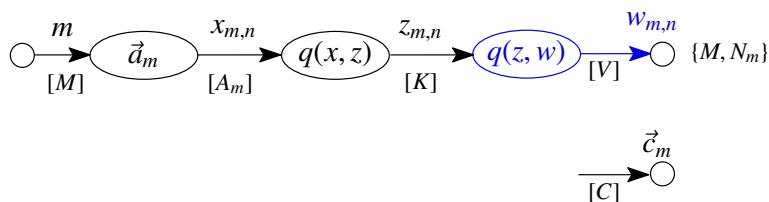
Compose model



$$p(x, \mathbf{z}, \dots | \cdot) \propto a_{m,x} q(x, \mathbf{z}) \dots$$

Each author only one field of expertise (topic distribution)
 → q -term $q(x, z)$ assigns topics to sampled author x (cf. ATM)

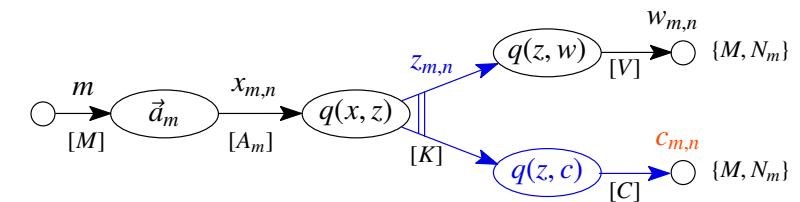
Compose model



$$p(x, z, \dots | \cdot) \propto a_{m,x} q(x, z) q(z, w) \dots$$

Topic distribution over words → can connect directly via $q(z, w)$

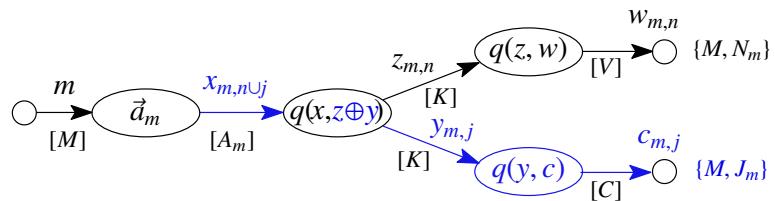
Compose model



$$p(x, z | \cdot) \propto a_{m,x} q(x, z) q(z, w) q(z, c)$$

Incorporate tags via $q(z, c)$ conditioned on the same topic
 → Problem: How to determine tag $c_{m,n}$ for word?

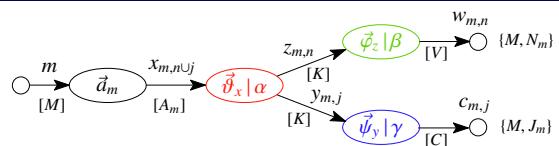
Compose model



$$p(x, z, y | \cdot) \propto a_{m,x} q(x, z \oplus y) q(z, w) q(y, c)$$

- Incorporate tag topics $y_{m,j}$ on separate sequence (m, j)
- Tag boosting: adjust tag influence via tag sequence length J_m

ETT1 model



Assembled q -terms:

$$p(x, z, y | \cdot) \propto a_{m,x} q(x, z \oplus y) q(z, w) q(y, c) \quad (4)$$

Easy expansion to standard Gibbs full conditionals:

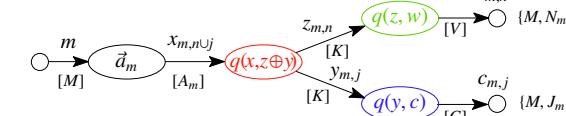
$$p(x_{m,n}=x, z_{m,n}=z | \cdot) \propto a_{m,x} \cdot \frac{n_x^{-\{x,z\}_{m,n}} + \alpha}{n_x^{-\{x,z\}_{m,n}} + K\alpha} \cdot \frac{n_z^{-z_{m,n}} + \beta}{n_z^{-z_{m,n}} + V\beta} \quad (5)$$

$$p(x_{m,j}=x, y_{m,j}=y | \cdot) \propto a_{m,x} \cdot \frac{n_x^{-\{x,y\}_{m,j}} + \alpha}{n_y^{-\{x,y\}_{m,j}} + K\alpha} \cdot \frac{n_y^{-y_{m,j}} + \gamma}{n_y^{-y_{m,j}} + C\gamma} \quad (6)$$

Retrieval via query likelihood model:

$$p(\vec{w} | a) = \prod_{w \in \vec{w}} \sum_z \vartheta_{a,z} \varphi_{z,w} \quad p(\vec{c} | a) = \prod_{c \in \vec{c}} \sum_y \vartheta_{a,y} \psi_{y,c} \quad (7)$$

ETT1 model



Assembled q -terms:

$$p(x, z, y | \cdot) \propto a_{m,x} q(x, z \oplus y) q(z, w) q(y, c) \quad (4)$$

Easy expansion to standard Gibbs full conditionals:

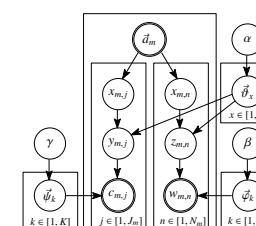
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$$p(x_{m,j}=x, y_{m,j}=y | \cdot) \propto a_{m,x} \cdot \frac{n_x^{-\{x,y\}_{m,j}} + \alpha}{n_y^{-\{x,y\}_{m,j}} + K\alpha} \cdot \frac{n_y^{-y_{m,j}} + \gamma}{n_y^{-y_{m,j}} + C\gamma} \quad (6)$$

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$$p(\vec{w} | a) = \prod_{w \in \vec{w}} \sum_z \vartheta_{a,z} \varphi_{z,w} \quad p(\vec{c} | a) = \prod_{c \in \vec{c}} \sum_y \vartheta_{a,y} \psi_{y,c} \quad (7)$$

Typical derivation method (Is it really that complex?)



(a) Expert–tag–topic model 1 (ETT1)
(Heinrich 2011)

$$p(\vec{w}, \vec{c}, \vec{d}, \vec{x}, \vec{z}, \vec{\alpha}, \vec{\beta}, \vec{\gamma} | \vec{a}, \vec{y}) = \int \prod_{m=1}^M \prod_{n=1}^{N_m} \prod_{j=1}^{J_m} \prod_{k=1}^K p(w_{m,n} | \vec{z}_{m,n}) p(z_{m,n} | \vec{d}_{m,n}) a_{m,n,j,k}$$

$$\cdot \prod_{k=1}^K p(\vec{\alpha}_k | \vec{d}_{m,n}) p(y_{m,j} | \vec{d}_{m,n}) a_{m,n,j,k} \cdot d\vec{\alpha}_k d\vec{y} \quad (E.3)$$

$$= \int \prod_{m=1}^M \prod_{n=1}^{N_m} \prod_{j=1}^{J_m} \prod_{k=1}^K p(w_{m,n} | \vec{z}_{m,n}) p(z_{m,n} | \vec{d}_{m,n}) \prod_{k=1}^K p(\vec{\phi}_k | \beta) d\vec{\phi}_k$$

$$\cdot \int \prod_{m=1}^M \prod_{n=1}^{N_m} \prod_{j=1}^{J_m} \prod_{k=1}^K p(z_{m,n} | \vec{d}_{m,n}) a_{m,n,j,k} \prod_{j=1}^J p(y_{m,j} | \vec{d}_{m,n}) a_{m,n,j,k} d\vec{d}_m \quad (E.4)$$

$$= \int \prod_{k=1}^K \frac{1}{\Delta(\vec{\phi}_k)} \prod_{j=1}^J \frac{n_{y_{m,j}} + \beta}{\Delta(\vec{\phi}_k)} d\vec{\phi}_k \cdot \int \prod_{k=1}^K \frac{1}{\Delta(\vec{\gamma})} \prod_{j=1}^J \frac{n_{y_{m,j}} + \gamma}{\Delta(\vec{\gamma})} d\vec{\phi}_k \quad (E.5)$$

$$= \int \prod_{k=1}^K \frac{\Delta(\vec{\theta}_k^{(1)} + \beta)}{\Delta(\vec{\theta}_k)} \cdot \frac{\Delta(\vec{\theta}_k^{(2)} + \gamma)}{\Delta(\vec{\gamma})} \prod_{j=1}^J \frac{\Delta(\vec{\theta}_k^{(1)} + \alpha) + \gamma}{\Delta(\vec{\theta}_k^{(2)} + \alpha)} \prod_{m=1}^M \prod_{n=1}^{N_m} \prod_{j=1}^{J_m} \frac{n_{y_{m,j}} + \alpha}{n_{y_{m,j}} + \gamma} \quad (E.6)$$

$$p(z_i=k, x_i=w_i | \vec{z}_{-i}, \vec{y}_{-i}, \vec{x}_{-i}, \vec{d}_{-i}, \vec{c}) = \frac{p(\vec{w}, \vec{z}, \vec{y}, \vec{x})}{p(\vec{w}, \vec{z}, \vec{y}, \vec{x}, \vec{d})} \cdot \frac{p(\vec{z} | \vec{d})}{p(\vec{z}_{-i} | \vec{d}_{-i})} \cdot \frac{p(\vec{x} | \vec{d})}{p(\vec{x}_{-i} | \vec{d}_{-i})} \quad (E.7)$$

$$\propto \frac{\Delta(\vec{\theta}_k^{(1)} + \beta)}{\Delta(\vec{\theta}_k^{(2)} + \beta)} \cdot \frac{\Delta(\vec{\theta}_k^{(2)} + \alpha)}{\Delta(\vec{\theta}_k^{(1)} + \alpha)} \cdot a_{m,x} \quad (E.8)$$

$$= \frac{\Gamma(n_{x,i} + \beta) \Gamma(n_{x,i} + V\beta)}{\Gamma(n_{x,i} + \beta) \Gamma(n_{x,i} + V\beta)} \cdot \frac{\Gamma(n_{x,i}^{(1)} + \alpha) \Gamma(n_{x,i}^{(2)} + K\alpha)}{\Gamma(n_{x,i}^{(1)} + \alpha) \Gamma(n_{x,i}^{(2)} + K\alpha)} \cdot a_{m,x} \quad (E.9)$$

$$= \frac{n_{x,i} + \beta}{n_{x,i} + V\beta} \cdot \frac{n_{x,i}^{(1)} + \alpha}{n_{x,i}^{(1)} + K\alpha} \cdot a_{m,x} \quad (E.10)$$

$$p(y_i=k, x_i=w_i | \vec{z}_{-i}, \vec{y}_{-i}, \vec{x}_{-i}, \vec{d}_{-i}, \vec{c}) \propto \frac{n_{y,i} + \gamma}{n_{y,i} + V\gamma} \cdot \frac{n_{y,i}^{(1)} + \alpha}{n_{y,i}^{(1)} + K\alpha} \cdot a_{m,x} \quad (E.11)$$

$$p(y_i=k, x_i=w_i | \vec{z}_{-i}, \vec{y}_{-i}, \vec{x}_{-i}, \vec{d}_{-i}, \vec{c}) \propto \frac{n_{y,i} + \gamma}{n_{y,i} + V\gamma} \cdot \frac{n_{y,i}^{(2)} + \alpha}{n_{y,i}^{(2)} + K\alpha} \cdot a_{m,x} \quad (E.12)$$

Model evaluation

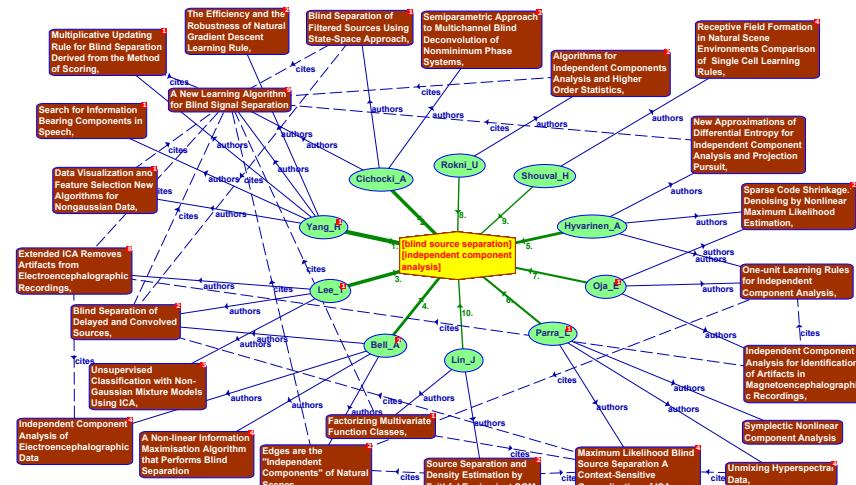


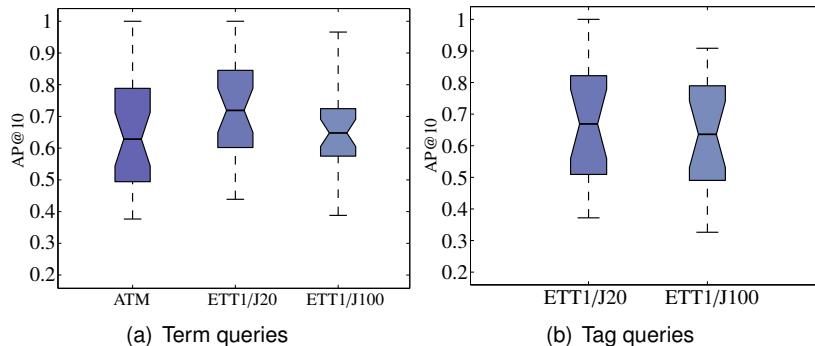
Figure: ETT1 example query in community browser.

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Retrieval and clustering results



- Term retrieval improved by tag influence during *training time*
- Mutual information between a-priori tag clusterings $p(c|a)$ and topic clusterings $p(z|a)$: $ETT1 \geq 1.002$ vs. $ATM = 0.865$.
- Semi-supervised features: find relevant items with missing tags
- Tag strength: bias towards strong tags in combinations

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Truncated average precision

$$AP@5 = \frac{1/2 + 2/4 + 3/5}{3} = 0.533$$

$$AP@5 = \frac{1/1 + 2/2 + 3/5}{3} = 0.867$$

Figure: Average precision at 5 (3 relevant documents in corpus).

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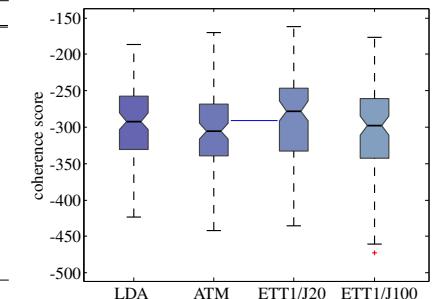
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Topic coherence results

Topic coherence (Mimno et al. 2011):

- \approx How often do top-ranked topic terms co-occur in documents?
- Re-enacts human judgement in topic intrusion experiments (Chang et al. 2009; Heinrich 2011)

Words in topic (choose worst match (A-F) in every group):					
1. A. orientation	2. A. likelihood	3. A. risk			
B. cortex	B. mixture	B. return			
C. visual	C. theorem	C. stock			
D. ocular	D. density	D. trading			
E. acoustic	E. em	E. processor			
F. eye	F. prior	F. prediction			
4. A. language	5. A. circuit	6. A. validation			
B. word	B. bayesian	B. set			
C. stress	C. analog	C. variance			
D. grammar	D. voltage	D. regression			
E. neural	E. vlsi	E. selection			
F. syllable	F. chip	F. bias			



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Overview

- Topic models – motivation and review
- Networks of mixed membership (NoMMs)
- Inference – a Gibbs “meta-sampler”
- NoMM typology and design
- Application to tag-enhanced expertise finding
- Conclusions and outlook

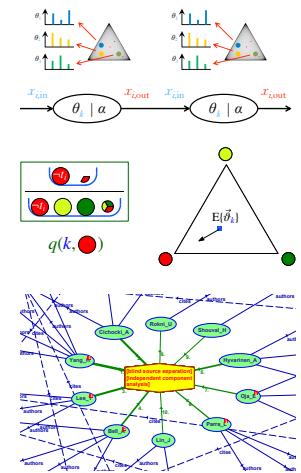
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Conclusions

- Networks of mixed membership:
Domain-specific compact representation
- Inference:
 - Generic Gibbs sampling: q -functions as central quantity in model behaviour
 - Gibbs meta-sampler: simplify implementation
 - Hybrid acceleration methods
 - Alternatives: variational Bayes (Heinrich and Goesele 2009), collapsed VB
- Typology and design method:
 - Model structure types: literature + novel
 - Building blocks for design with predictable properties
- Application:
 - Expert–tag–topic model demonstrates design
 - Tags improve retrieval and topic coherence



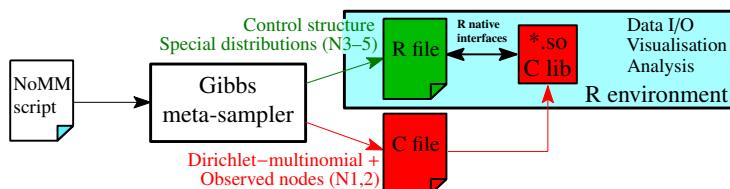
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Towards an R-based Gibbs meta-sampler

- R environment becoming popular for topic models, e.g.:
 - `topicmodels` package implementing general and various special cases (Grün and Hornik 2011), based on text mining package `tm`
 - `lda` package with LDA, supervised, relational topic models (Blei et al. 2003; Blei and McAuliffe 2007; Chang and Blei 2009)
- Vision: Use Gibbs meta-sampler as front-end to create R-based high-performance code ↔ use R as experimental front-end



- Extend to non-parametric distributions, e.g., based on DPpackage (Jara et al. 2012):
 - NoMMs as polymorphism of parametric and non-parametric models (with different Bayesian networks)

Q+A

<http://arbylon.net/resources.html>

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